

# Filtering Data using Frequency Domain Filters

Wouter J. Den Haan  
London School of Economics

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August 27, 2014

# Overview

- Intro
  - lag operator
  - Why frequency domain?
- Fourier transform
- Data as cosine waves
- Spectrum
- Filters & I(1) processes
- Band-pass filters
- HP filter

# Lag operator

$$x_{t-1} = Lx_t$$

$$x_{t-2} = Lx_{t-1} = LLx_t = L^2x_t$$

$$x_{t+1} = L^{-1}x_t$$

$$\Delta x_t = (1 - L)x_t$$

# Lag operator

$$x_t = \rho x_{t-1} + \varepsilon_t \text{ with } |\rho| < 1$$

$$x_t = \rho L x_t + \varepsilon_t$$

$$(1 - \rho L) x_t = \varepsilon_t$$

$$x_t = \frac{\varepsilon_t}{1 - \rho L}$$

# Lag operator

$$\frac{1}{1-\rho} = 1 + \rho + \rho^2 + \rho^3 + \dots \text{ if } |\rho| < 1$$

$$\frac{1}{1-\rho L} = 1 + \rho L + \rho^2 L^2 + \rho^3 L^3 + \dots \text{ if } |\rho L| < 1$$

# Why go to frequency domain

- ① Extract that part from the data that your model tries to explain
  - e.g., business cycle frequencies
- ② Some calculations are easier in frequency domain
  - e.g., auto-covariances of ARMA processes
  - not the focus on this lecture

# Fourier Transform

Given a sequence  $\{x_j\}_{-\infty}^{\infty}$  the Fourier transform is defined as

$$F(\omega) = \sum_{j=-\infty}^{\infty} x_j e^{-i\omega j}$$

If  $x_j = x_{-j}$  then

$$F(\omega) = x_0 + \sum_{j=1}^{\infty} x_j \left( e^{-i\omega j} + e^{i\omega j} \right) = x_0 + \sum_{j=1}^{\infty} 2x_j \cos(\omega j)$$

and the Fourier transform is a real-valued symmetric function.

# Fourier Transform

- It is just a definition!
  - which turns out to be useful



# Inverse Fourier Transform

- Given a Fourier Transform  $F(\omega)$ , one can back out the original sequence using

$$x_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) e^{i\omega j} d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) (\cos \omega j + i \sin \omega j) d\omega$$

and if  $F(\omega)$  is symmetric then

$$x_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) \cos \omega j d\omega = \frac{1}{\pi} \int_0^{\pi} F(\omega) \cos \omega j d\omega$$

- derivation is in the notes

# Thinking differently about a time series

- You can take the Fourier transform of any sequence
- So you can also take it of a time series
  - take finite analogue if time series is finite

# Thinking differently about a time series

- Finite Fourier transform of  $\{x_t\}_{t=1}^T$ , scaled by  $\sqrt{T}$

$$\tilde{x}(\omega) = \frac{1}{\sqrt{T}} \sum_{t=1}^T e^{-i\omega t} x_t.$$

- Let

$$\omega_j = -\pi + (j-1)2\pi/T \text{ for } j = 1, \dots, T+1$$

# Formulas

$\tilde{x}(\omega)$  can be expressed as

$$\tilde{x}(\omega) = |\tilde{x}(\omega)| e^{i\phi(\omega)}$$

with

$$\tilde{x}(-\omega) = |\tilde{x}(\omega)| e^{-i\phi(\omega)}$$

# Thinking differently about a time series

- The *finite* inverse Fourier transform is given by

$$\begin{aligned}x_t &= \frac{1}{\sqrt{T}} \sum_{|\omega_j| \leq \pi} e^{i\omega_j t} \tilde{x}(\omega_j) \\ &= \frac{1}{\sqrt{T}} \sum_{|\omega_j| \leq \pi} |\tilde{x}(\omega)| e^{i\omega_j t} e^{i\phi(\omega)} \\ &= \frac{1}{\sqrt{T}} \left( \tilde{x}(0) + \sum_{0 < \omega_j \leq \pi} |\tilde{x}(\omega)| \left( e^{i(\omega_j t + \phi(\omega))} + e^{-i(\omega_j t + \phi(\omega))} \right) \right).\end{aligned}$$

# Thinking differently about a time series

Using

$$e^{i\delta(\omega)} = \cos \delta(\omega) + i \sin \delta(\omega)$$

or

$$e^{i\delta(\omega)} + e^{-i\delta(\omega)} = 2 \cos \delta(\omega)$$

gives

$$x_t = \frac{1}{\sqrt{T}} \left( \tilde{x}(0) + 2 \sum_{0 < \omega_j \leq \pi} |\tilde{x}(\omega_j)| \cos(\omega_j t + \phi(\omega_j)) \right)$$

# Thinking differently about a time series

$$x_t = \frac{1}{\sqrt{T}} \left( \tilde{x}(0) + 2 \sum_{\omega_j \leq \pi} |\tilde{x}(\omega_j)| \cos(\omega_j t + \phi(\omega_j)) \right)$$

Simple interpretation:

- $x_t$  : dependent variable ( $T$  observations)
- $\omega_j t$  :  $T$  independent variables
- get perfect fit by choosing  $|\tilde{x}(\omega_j)|$  and  $\phi(\omega_j)$
- if  $|\tilde{x}(\omega_j)|$  is high than that frequency is important for time variation  $x_t$

# (Informally) thinking about the variance

- What is the variance of  $x_t$ ?
- Focus on the case with  $E[x_t] = 0$
- $E[x_t^2]$  depends on  $E\left[\left(\sum_{\omega_j < \pi} \tilde{x}(\omega_j)\right)^2\right]$
- Fortunately,  $\lim_{T \rightarrow \infty} E[\tilde{x}(\omega_j)\tilde{x}(\omega_i)] = 0$
- variance of  $x_t$  depends just on sum of the squared  $|\tilde{x}(\omega_j)|$  terms (or on the integral in the limit)



# Spectrum

Given a sequence  $\{\gamma_j\}_{-\infty}^{\infty}$  of autocovariances of a scalar process then the spectrum is defined as

$$S(\omega) = \frac{1}{2\pi} \sum_{j=-\infty}^{\infty} \gamma_j e^{-i\omega j} = \frac{1}{2\pi} \left( \gamma_0 + \sum_{j=1}^{\infty} 2\gamma_j \cos(\omega j) \right)$$

And according to the inverse

$$\gamma_0 = \int_{-\pi}^{\pi} S(\omega) d\omega$$

# Spectrum

So spectrum is just the Fourier transform of the covariances

# Spectrum of transformed series

If

$$y_t = \sum_{j=-\infty}^{\infty} b_j x_{t-j} = b(L)x_t$$

Then

$$S_y(\omega) = b(e^{-i\omega})b(e^{i\omega})S_x(\omega) = \left| b(e^{-i\omega}) \right|^2 S_x(\omega)$$

- $|\cdot|$  is the modulus of the complex number
- Note that  $b(e^{-i\omega})$  is the Fourier transform of the  $b_j$  sequence
- For symmetric filters we have  $b(e^{-i\omega}) = b(e^{i\omega})$

## Examples - white noise

$$x_t = \varepsilon_t \text{ and } E[\varepsilon_t \varepsilon_{t-j}] = 0 \text{ for } j \neq 0$$

$$\begin{aligned} S(\omega) &= \frac{1}{2\pi} \sum_{j=-\infty}^{\infty} \gamma_j e^{-i\omega j} \\ &= \frac{1}{2\pi} \left( \gamma_0 + \sum_{j=1}^{\infty} 2\gamma_j \cos(\omega j) \right) \\ &= \frac{\gamma_0}{2\pi} \end{aligned}$$

## Examples - AR(1)

$$y_t = \rho y_{t-1} + x_t$$

$$y_t = \frac{x_t}{1 - \rho L}$$

$$\begin{aligned} S_y(\omega) &= \left| \frac{1}{1 - \rho e^{-i\omega}} \right|^2 S_x(\omega) \\ &= \frac{1}{1 - \rho e^{-i\omega}} \frac{1}{1 - \rho e^{+i\omega}} S_x(\omega) \\ &= \frac{1}{1 - \rho (e^{-i\omega} + \rho e^{+i\omega}) + \rho^2} S_x(\omega) \\ &= \frac{1}{1 - 2\rho \cos \omega + \rho^2} S_x(\omega) \end{aligned}$$

## Examples - VAR(P)

$$y_t = \sum_{j=1}^J A_j y_{t-j} + x_t$$

$$y_t = \left( I - \sum_{j=1}^J A_j L^j \right)^{-1} x_t$$

$$S_y(\omega) = \left( I - \sum_{j=1}^J A_j e^{-j\omega} \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' e^{j\omega} \right)^{-1}$$

## Examples - VAR(P)

$$y_t = \sum_{j=1}^J A_j y_{t-j} + x_t$$

$$\begin{aligned} S_y(0) &= \left( I - \sum_{j=1}^J A_j e^{-j \times 0} \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' e^{j \times 0} \right)^{-1} \\ &= \left( I - \sum_{j=1}^J A_j \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' \right)^{-1} \end{aligned}$$

This last formula is useful in calculating Heteroskedastic and Autocorrelation Consistent (HAC) variance-covariance estimators

# What is a filter?

- A filter is just a transformation of the data
- Typically with a particular purpose
  - e.g. remove seasonality or "noise"
- Filters can be expressed as

$$x_t^f = b(L)x_t$$
$$b(L) = \sum_{j=-\infty}^{\infty} b_j L^j$$



# Examples of filters

$$b(L) = 1 - L \implies x_t^f = x_t - x_{t-1}$$

$$b(L) = -\frac{1}{2}L^{-1} + 1 - \frac{1}{2}L$$

# I(0) and I(1) processes

- I(0) are stationary processes
- $x_t$  is I(1) if  $\Delta x_t$  is stationary

# I(0) and I(1) processes

$$x_t = B(L) \varepsilon_t,$$

where  $\varepsilon_t$  is white noise.

- If  $x_t$  is I(1), then  $B(1) = \infty$
- If  $B(1) < \infty$ , then  $x_t$  is stationary

(same holds if  $\varepsilon_t$  is stationary)

# Filters that induce stationarity

- Suppose that  $x_t$  is I(1). Thus

$$(1 - L)x_t = z_t$$

with  $z_t$  an I(0) process.

- Filtering gives

$$x_t^f = b(L)x_t$$

- Question: When is  $x_t^f$  I(0)?

## Filters that induce stationarity

Define  $\bar{b}(L)$  such that

$$b(L) = (1 - L)\bar{b}(L).$$

If

$$\bar{b}(1) < \infty,$$

then  $x_t^f = b(L)x_t$  is stationary even if  $x_t$  is I(1).

$$\begin{aligned}x_t^f &= b(L)x_t \\&= (1 - L)\bar{b}(L)x_t \\&= (1 - L)\bar{b}(L)\frac{z_t}{(1 - L)} \\&= \bar{b}(L)z_t\end{aligned}$$

# Spectrum of filtered series

$$y_t = \sum_{j=-\infty}^{\infty} b_j x_{t-j} = b(L)x_t$$

Then

$$S_y(\omega) = b(e^{-i\omega})b(e^{i\omega})S_x(\omega) = \left| b(e^{-i\omega}) \right|^2 S_x(\omega)$$

- $|\cdot|$  is the modulus of the complex number
- Note that  $b(e^{-i\omega})$  is the Fourier transform of the  $b_j$  sequence
- For symmetric filters we have  $b(e^{-i\omega}) = b(e^{i\omega})$

# Band-pass filters

$$y_t = b(L)x_t$$

Goal:

$$S_y(\omega) = \begin{cases} S_x(\omega) & \text{if } \omega_L \leq |\omega| \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

Thus we need

$$b(e^{-i\omega}) = \begin{cases} 1 & \text{if } \omega_L \leq |\omega| \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

- How to find the coefficients  $b_j$  that correspond with this?
- Since  $b(e^{-i\omega})$  is a Fourier transform we can use the inverse of the Fourier transform

# Coefficients of band-pass filters

Inverse of the Fourier transform for  $b_0$ :

$$\begin{aligned} b_j &= \frac{1}{2\pi} \int_{-\pi}^{\pi} b(e^{-i\omega}) e^{i\omega j} d\omega \\ &= \frac{1}{2\pi} \left( \int_{-\omega_H}^{-\omega_L} 1 \times e^{i\omega j} d\omega + \int_{\omega_L}^{\omega_H} 1 \times e^{i\omega j} d\omega \right) \\ &= \frac{\omega_H - \omega_L}{\pi} \end{aligned}$$



# Coefficients of band-pass filters

Inverse of the Fourier transform for  $b_j$ :

$$\begin{aligned}
 b_j &= \frac{1}{2\pi} \int_{-\pi}^{\pi} b(e^{-i\omega}) e^{i\omega j} d\omega \\
 &= \frac{1}{2\pi} \left( \int_{-\omega_H}^{-\omega_L} 1 \times e^{i\omega j} d\omega + \int_{\omega_L}^{\omega_H} 1 \times e^{i\omega j} d\omega \right) \\
 &= \frac{1}{2\pi} \left( \int_{\omega_L}^{\omega_H} (e^{i\omega j} + e^{-i\omega j}) d\omega \right) \\
 &= \frac{1}{2\pi} \int_{\omega_L}^{\omega_H} 2 \cos(\omega j) d\omega \\
 &= \frac{1}{\pi j} \left[ \sin \omega j \right]_{\omega_L}^{\omega_H} = \frac{\sin(\omega_H j) - \sin(\omega_L j)}{\pi j}
 \end{aligned}$$

Note that you can also get  $b_0$  from the last line by using l'Hopital's rule

# Properties of the band-pass filter

$$b(L) = \sum_{j=-\infty}^{\infty} b_j L^j$$

- $b(L)$  is a polynomial of  $L$ . Consider the roots to the problem:

$$b(L) = 0$$

If  $L = 1$  is a root of the problem, then we have

$$b(L) = (1 - L)\bar{b}(L) \quad \text{with } \bar{b}(1) < \infty$$

# Properties of the band-pass filter

- But  $L = 1$  is a root of our filter as long as  $\omega_L > 0$ , because then we have by construction

$$b(1) = b(e^{-i0}) = 0$$

Clearly, if you do not filter out the zero frequency then you do not induce stationarity

## More on I(1) processes

- Discussion above showed

$$x_t^f = b(L)x_t \text{ is stationary even if } x_t \text{ is I(1)}$$

- This is not enough to show that the filter does what it is supposed to do, which is
  - ensure the spectrum of the filtered series is zero for the excluded frequencies
  - ensure the spectrum of the filtered series equals the spectrum of the original series for the included frequencies
- The second condition requires a definition of the spectrum for I(1) processes

# Spectrum for I(1) processes

Consider an arbitrary I(1) process

$$x_t = \frac{z_t}{1-L}$$

Let

$$x_{\rho,t} = \frac{z_t}{1-\rho L}$$

For  $\rho < 1$  the spectrum of  $x_{\rho,t}$  is well defined

$$S_{\rho,x}(\omega) = \frac{1}{1 - 2\rho \cos(\omega) + \rho^2} S_z(\omega)$$

Define the spectrum of  $x_t$  as

$$S_x(\omega) = \lim_{\rho \rightarrow 1} S_{\rho,x}(\omega)$$

This is well defined for all  $\omega > 0$ , but not for  $\omega = 0$ .

# Filtered I(1) process

$$x_t^f = b(L)x_t$$

Let  $b(L)$  be a band-pass filter, that is,

$$b(e^{-i\omega}) = \begin{cases} 1 & \text{if } \omega_L \leq \omega \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

# Filtered I(1) process

- if  $\omega_L > 0$ , then it can be shown that
  - $x_t^f$  is stationary (because as shown above we know that  $b(1) = 0$ ) and
  - $S_{x^f}(\omega) = \begin{cases} S_x(\omega) & \text{if } \omega_L \leq \omega \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$
- That is, using the definition of the Spectrum for I(1) processes the filter does exactly what it is supposed to do
- Proof is simple; The only tricky thing is to prove is that

$$b(e^{-i0})S_x(0) = 0$$

## Practical Filter

- The filter constructed so far is two-sided and infinite order
- Implementable version would be to use

$$\tilde{b}(L) = \sum_{j=-J}^J b_j L^j$$

But it is not necessarily the case that

$$\tilde{b}(1) = 0$$

So instead use

$$a(L) = \sum_{j=-J}^J a_j L^j$$

with

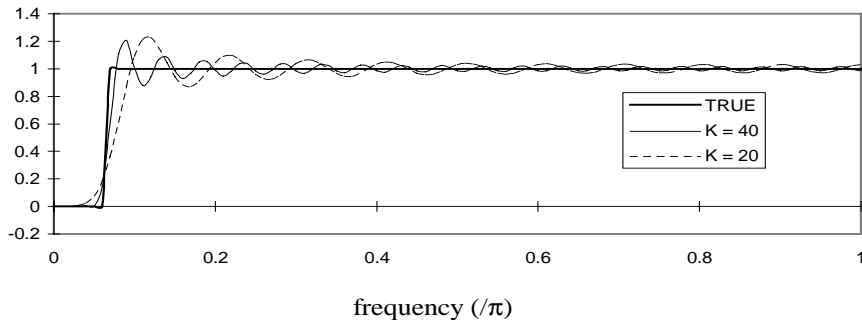
$$a_j = b_j + \mu \quad \text{and} \quad \mu = -\frac{\sum_{j=-J}^J b_j}{2J+1}$$



# Properties practical filter

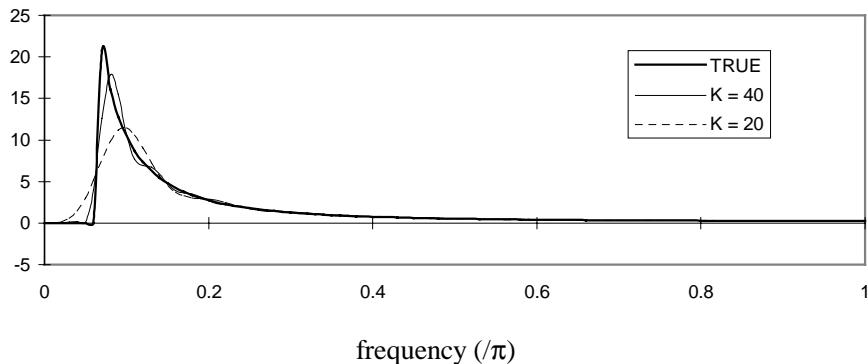
FIGURE 3.1: SPECTRA OF FILTERED PROCESSES ( $\omega_1 = \pi/16, \omega_2 = \pi$ )

A: White Noise (Squared Gain)



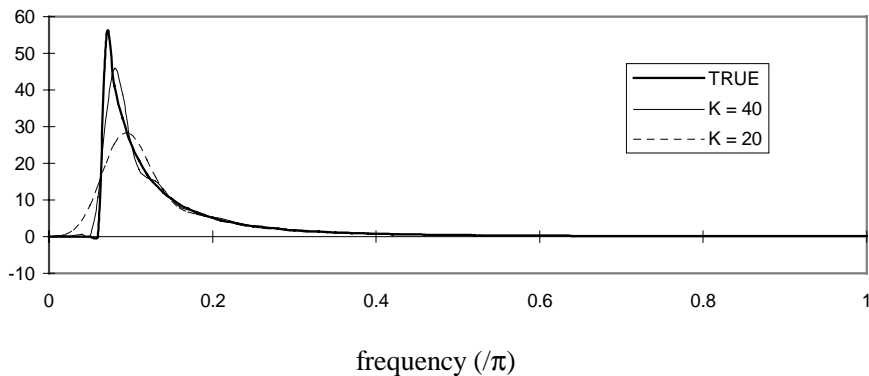
# Properties practical filter

B: AR(1) with Coefficient equal to 0.95



# Properties practical filter

C: Integrated AR(1) with Coefficient equal to 0.4



# Hodrick-Prescott Filter

- The HP trend,  $x_{\tau,t}$  is defined as follows

$$\begin{aligned} & \{x_{\tau,t}\}_{t=1}^T \\ & = \\ & \arg \min_{\{x_{\tau,t}\}_{t=1}^T} \sum_{t=2}^{T-1} (x_t - x_{\tau,t})^2 + \lambda \sum_{t=2}^{T-1} \left\{ \left[ \begin{array}{c} (x_{\tau,t+1} - x_{\tau,t}) \\ - (x_{\tau,t} - x_{\tau,t-1}) \end{array} \right]^2 \right\} \end{aligned}$$

# Hodrick-Prescott Filter

- $\lambda = 1,600$  standard for quarterly data
- the HP filter is then approximately equal to a band-pass filter with  $\omega_L = \pi/16$  and  $\omega_H = \pi$ .
  - That is, it keeps that part of the series associated with cycles that have a period less than 32 ( $=2\pi/(\pi/16)$ ) periods (i.e. quarters).

# Understanding filtered data is tricky

- Is filtered white noise serially uncorrelated?
- Are the filtered price level and filtered output positively correlated in a model with only demand shocks?  
(example below is from Den Haan 2000)

# Simple demand shock model

- Output is demand determined

$$y_t = y_t^d = D_t - P_t$$

- Demand is given by

$$(1 - \lambda_1 L)(1 - \lambda_2 L)(1 - \lambda_3 L) D_t = \varepsilon_t$$

with  $-1 < \lambda_3 < \lambda_2 < \lambda_1 \leq 1$

- Output is given by

$$y_t^s = a + bt$$

# Simple demand shock model

- Equilibrium price level  $\tilde{P}_t$  satisfies

$$\tilde{P}_t = D_t - y_t^s$$

- Actual prices adjust gradually

$$P_t = (1 - \beta) P_{t-1} + \beta \tilde{P}_t$$



# Simple demand shock model

## Solution

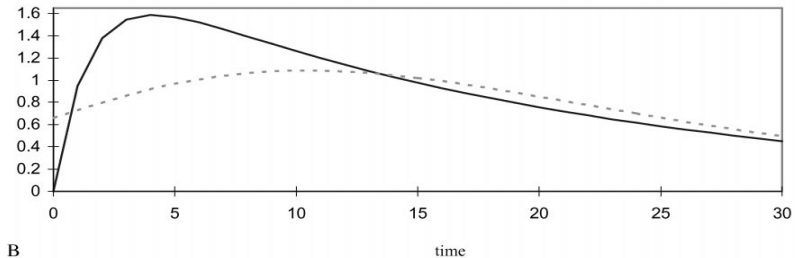
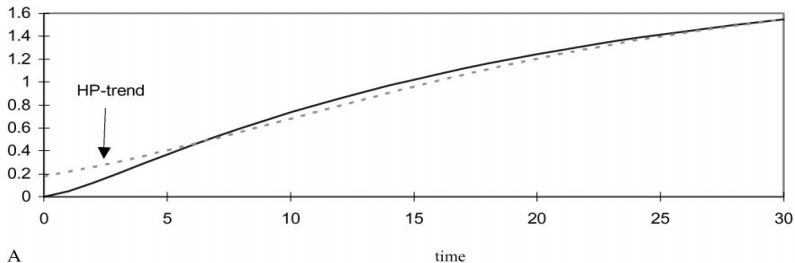
- Price level

$$P_t = \frac{\beta \varepsilon_t}{(1 - (1 - \beta)L)(1 - \lambda_1 L)(1 - \lambda_2 L)(1 - \lambda_3 L)}$$

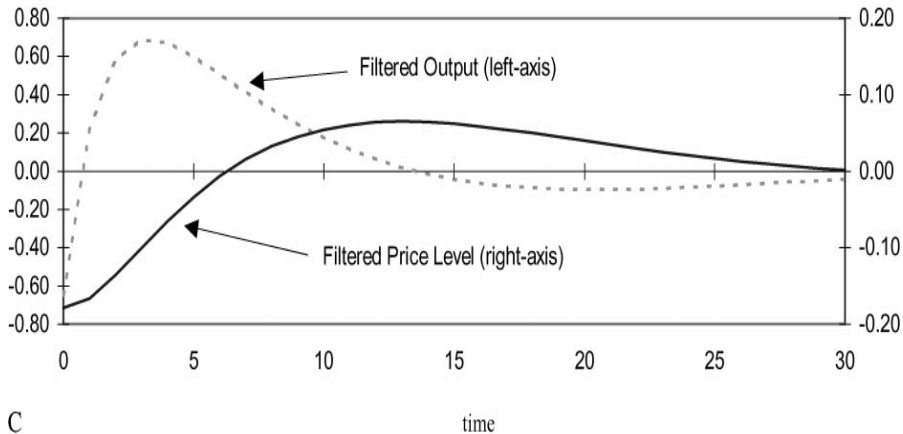
- Output

$$y_t = \frac{(1 - \beta)(1 - L)\varepsilon_t}{(1 - (1 - \beta)L)(1 - \lambda_1 L)(1 - \lambda_2 L)(1 - \lambda_3 L)}$$

# Positive correlation for unfiltered series



# Negative correlation for filtered series



C

# References

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